

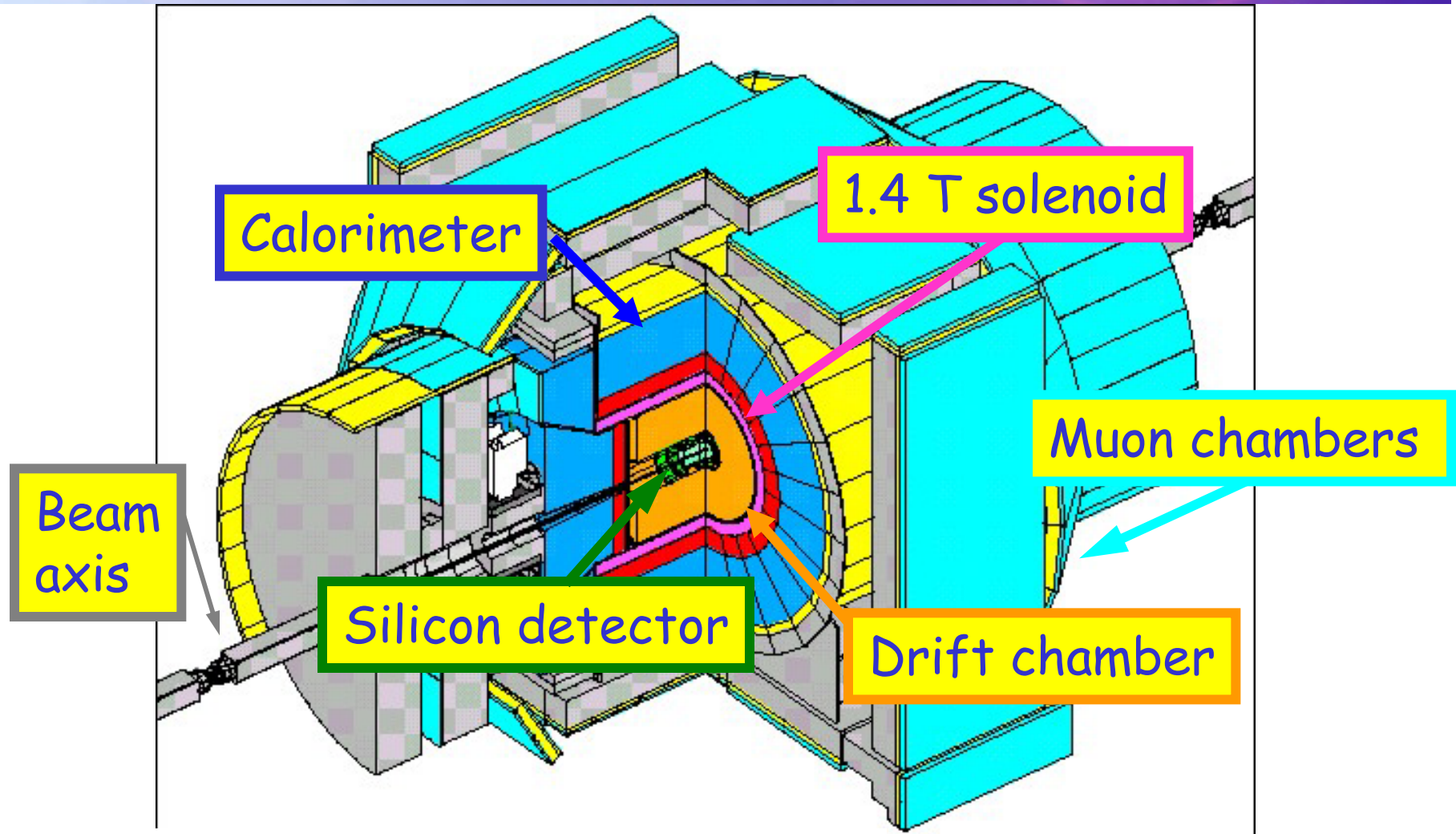
The CDF Silicon Vertex Trigger

Bill Ashmanskas
Argonne National Laboratory
(for the CDF-II Collaboration)
May 30, 2003

Outline

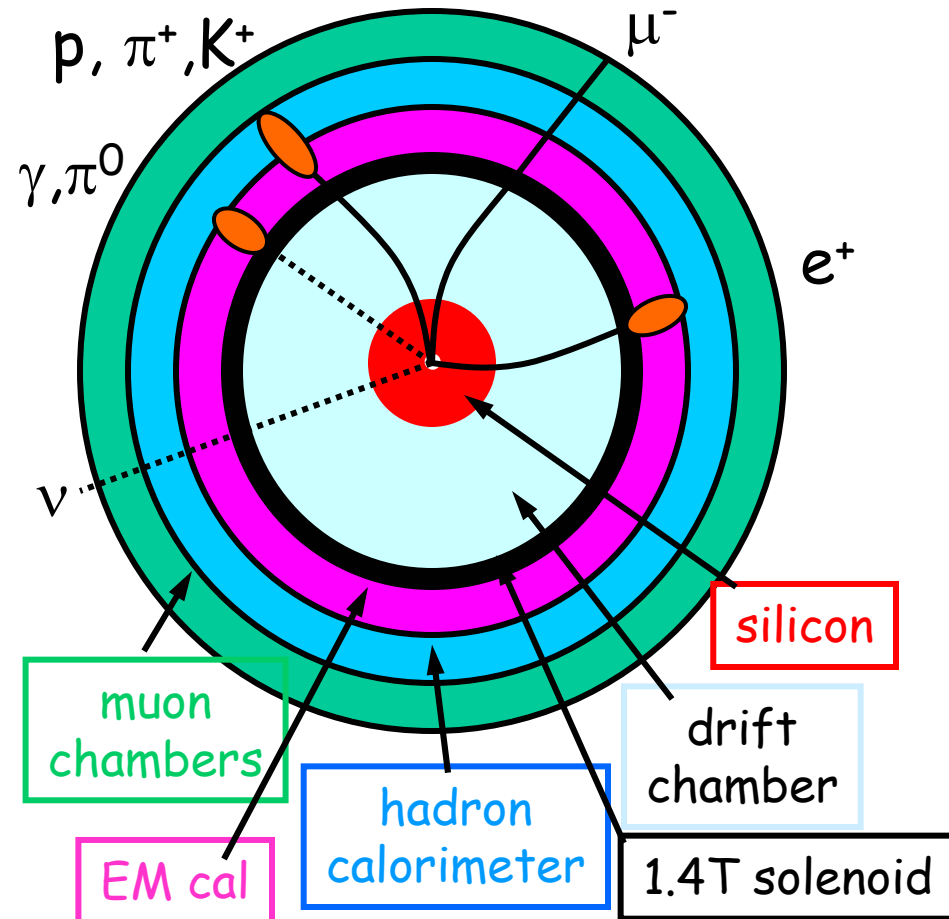
- CDF trigger overview → focus on SVT
- How SVT works (performance)
- Why SVT works (diagnostics/flexibility)

CDF Detector



- CDF: multi-purpose experiment, broad physics program
- Tevatron: $E_{CM}=1.96$ TeV, $T_{\text{bunch}} = 396$ (132) ns, $L \sim 10^{32} \text{cm}^{-2}\text{s}^{-1}$

CDF trigger (detector) signatures



Trigger exploits a wide variety of signatures ...

- e, μ from W, Z, SUSY, b
- γ, jet, ν (E imbalance), $\tau, b \text{ jet}, \dots$
- "Displaced" hadrons from bottom and charm decay

... to distinguish processes with a wide range of rates

- $\sim 50 \text{ mb}$ total inelastic
- $\sim 100 \text{ } \mu\text{b}$ bottom, charm
- $\sim 10 \text{ } \mu\text{b}$ $B, p_T > 6 \text{ GeV}, |y| < 1$
- $\sim 2 \text{ nb}$ $W \rightarrow e\nu$
- $\sim 5 \text{ pb}$ top

Many trigger signatures use drift chamber tracks, e.g. coincidence of D.C. track with EM cal, muon stub, silicon hits

CDF three-level trigger

rates (approx)

7 MHz



35 kHz



350 Hz



70 Hz

FE digitizes (silicon S&H)

Level 1: $\sim 5.5 \mu\text{sec}$ (42-stage pipeline)

- drift chamber tracks (+ calorimeter, muon, ...)
- look for 2 tracks with momenta $> 2 \text{ GeV}$

FE boards store to buffer (silicon digitizes/sends)

Level 2: $\sim 30 \mu\text{sec}$

- fast silicon tracking (+ cal clustering, shower max, ...)
- look for 2 tracks with impact parameters $> 120 \mu\text{m}$

FE crates transmit to event builder

Level 3: $\sim 1 \text{ second}$ (using ~ 250 PCs in parallel)

- full event reconstruction; data compression
 - full-precision tracking (includes stereo)
- confirm hardware tracks; form invariant masses

data logger writes event to disk

track trigger
b+c purity
 $\sim 0.1\%$



$\sim 1\%$



$\sim 50\%$



$\sim 90\%$

New triggers → a paper from first 12pb⁻¹

CDF approves first Run II paper

by Kurt Resselmann

Scientists at CDF have announced that they will soon release the first publication based on data obtained from Fermilab's Collider Run II. An internal CDF seminar scheduled for March 7 is likely to be the last step of an elaborate, six-month review process. Barring any objections from members of the CDF collaboration, scientists will submit a mass measurement of particles containing charm quarks to the journal *Physical Review D*.

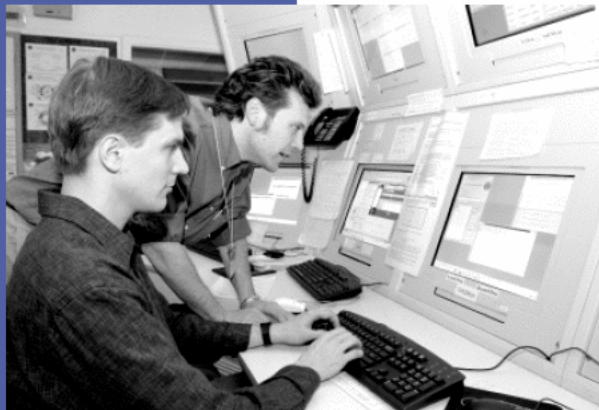
"It's not a major discovery," said CDF scientist Christopher Paus, a professor at MIT. "It's bread-and-butter physics. Our mass difference between the D^+ and D_s^+ particles is within the world average. Even more important, the paper is back."

This is not to say that the CDF scientists or their colleagues at the DZero experiment had ever disappeared. Over the years, the collaborations have published hundreds of papers from experiments that took place from 1992 to 1996. The first of a flood of publications expected from Run II.

It often takes many months or even years before a scientist is ready to publish results of a specific analysis. In the case of the CDF, it takes almost as much time to convince other members of the collaboration that an analysis was done right and that its conclusions are valid.

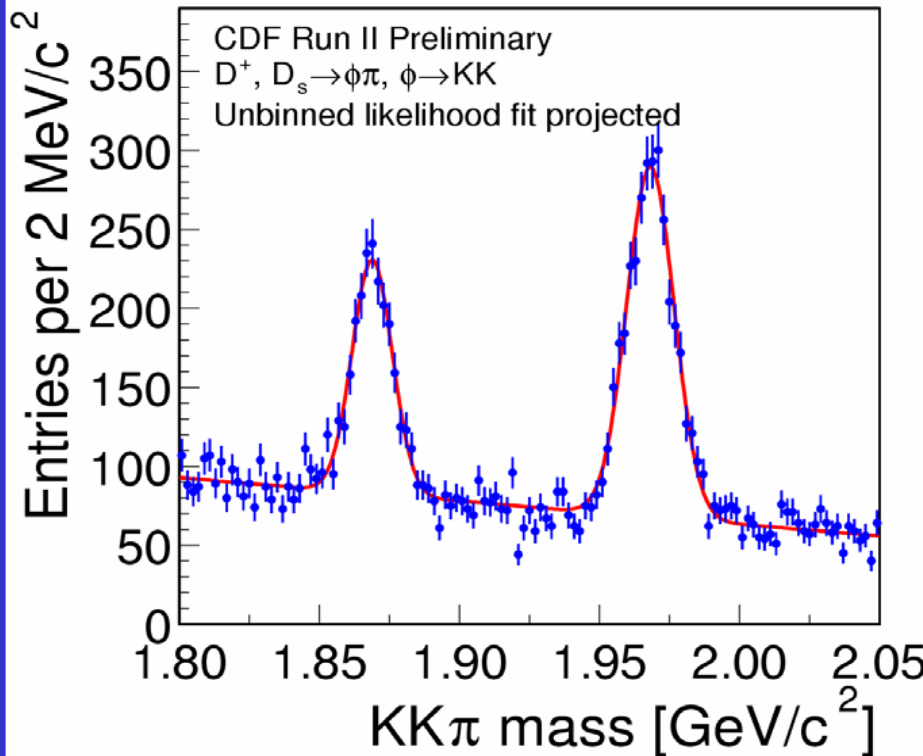
"Our results are solid. For or off of the collaboration. Every share value collab mem chanc and t used. If an and p quest bless mont that s never

Graduate student Ivan Furic (left) and assistant professor Christoph Paus, both CDF scientists from MIT, carried out the analysis for the first publication of Run II results.



Measurement of the Mass Difference $m(D_s^+) - m(D^+)$ at CDF II

D. Acosta,¹⁴ T. Affolder,⁷ M. H. Ahn,²⁵ T. Akimoto,⁵² M. G. Albrow,¹³ B. Alcorn,¹³ C. Alexander,⁴⁰ D. Allen,¹³ D. Allspach,¹³ P. Amaral,¹⁰ D. Ambrose,⁴⁰ S. R. Amendolia,⁴¹ D. Amidei,³⁰ J. Amundson,¹³ A. Anastassov,⁴⁷ J. Anderson,¹³ K. Anikeev,²⁹ A. Annovi,⁴¹ J. Antos,¹ M. Aoki,⁵² G. Apollinari,¹³ J.-F. Arguin,⁵⁰ T. Arisawa,⁵⁴ A. Artikov,¹¹ T. Asakawa,⁵² W. Ashmanskas,¹⁰ A. Attal,⁶ C. Avanzini,⁴¹ F. Azfar,³⁸ P. Azzi-Bacchetta,²⁹ M. Babik,¹³ N. Bacchetta,³⁹ H. Bachacou,²⁶ W. Badgett,¹³ S. Bailey,¹⁸ J. Bakken,¹³ A. Barbaro-Galtieri,²⁶ A. Bardi,⁴¹ M. Bari,⁵¹ G. Barker,²³ V. E. Barnes,⁴³ B. A. Barnett,²²



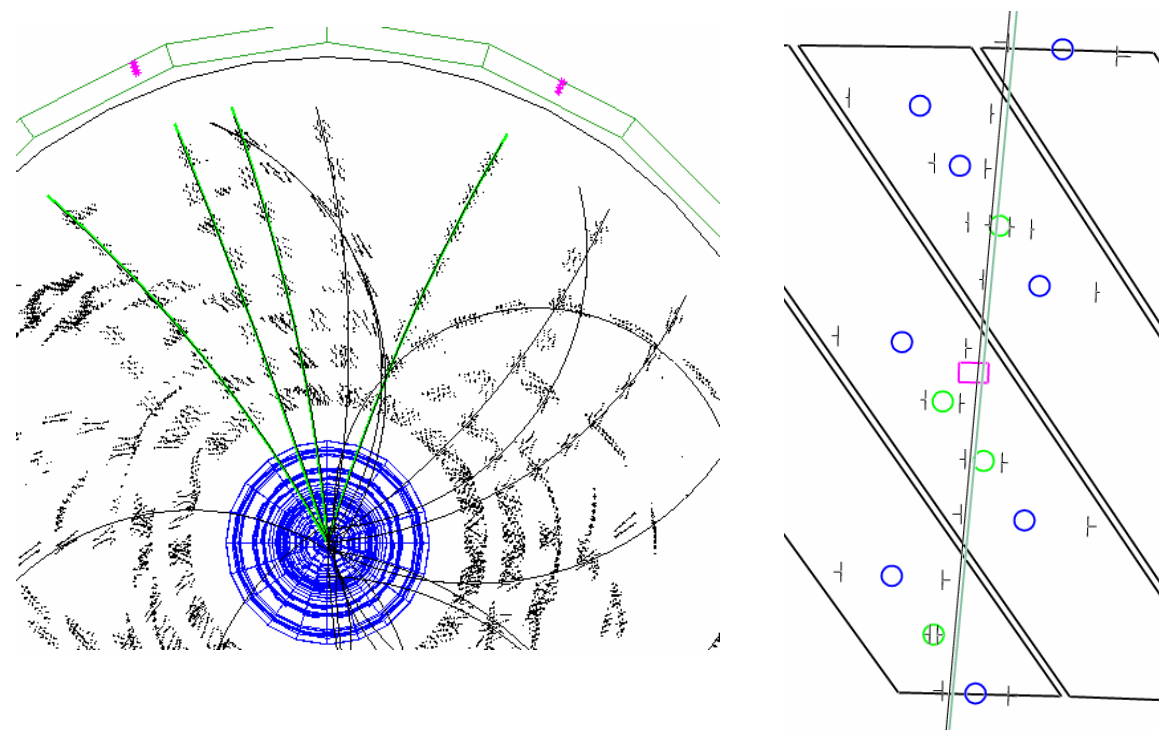
B. Bedeschi,⁴¹ S. Behari,²² J. Bering,¹² A. Beretvas,¹³ Blocker,⁴ K. Bloom,³⁰ v.,²⁹ P. S. L. Booth,²⁷ nberg,³¹ W. Brown,¹³ Burkett,¹⁸ G. Busetto,³⁹ M. Campanelli,¹⁶ Carosi,⁴¹ K. Carrell,⁴⁹ ito,²¹ J. T. Chandler,⁵⁶ rtok,⁵ G. Chiarelli,⁴¹ okheli,¹¹ M. L. Chu,¹ i. Cisko,¹³ A. G. Clark,¹⁶ very,⁴⁵ J. Conway,⁴⁷ albertson,¹³ C. Currat,²⁶ avila,¹³ J. Dawson,² Dell'Orso,⁴¹ R. DeMaat,¹³ erwent,¹³ G. Derylo,¹³ Donati,⁴¹ F. Donno,⁴¹ llinger,³³ I. Dunietz,¹³ M. Erdmann,²³ Feild,⁵⁶ M. Feindt,²³ agan,³¹ B. Flaughner,¹³ H. Frisch,¹⁰ J. Fromm,¹³ Ganel,⁴⁹ C. Garcia,³⁵ Jay,⁵⁶ H. Gerberich,¹² Giannetti,⁴¹ A. Gibson,²⁶ golev,¹¹ D. Glenzinski,¹³ omez,⁸ M. Goncharov,⁴⁸ uliancos,⁴⁵ J. Grado,¹³ C. Grosso-Pilcher,¹⁰ A. Hahn,¹³ K. Hahn,⁴⁰ H. Hapacher,¹⁵ K. Hara,⁵²

glon,⁵⁰ K. M. Harris,⁴⁹ F. Hartmann,²⁹ K. Hatakeyama,⁴⁵ J. Hauser,⁶ B. Heinemann,²⁷ J. Heinrich,⁴⁰ A. Heiss,²³ M. Hennecke,²³ R. Herber,¹³ s,¹³ C. Hill,⁷ D. Hirschbuehl,²³ A. Hocker,⁴⁴ J. Hoff,¹³ K. D. Hoffman,¹⁰ Holloway,²¹ S. Holm,¹³ D. Holmgren,¹³ S. Hou,¹ M. A. Houlden,²⁷ yk,¹³ P. Hubbard,¹³ R. E. Hughes,³⁵ B. T. Huffman,³⁸ J. Humbert,¹³ lela,⁷ G. Introzzi,⁴¹ M. Iori,⁴⁶ I. Ishizawa,⁵² C. Issever,⁷ A. Ivanov,⁴⁴ es,³⁰ D. Jang,⁴⁷ J. Jarrell,³³ D. Jeans,¹⁶ H. Jensen,¹³ R. Jetton,¹³ os,¹³ S. Y. Jun,⁹ T. Junk,²¹ J. Kallenbach,¹³ T. Kamon,⁴⁸ J. Kang,³⁰ n,³⁰ S. Kartal,¹³ H. Kasha,⁵⁶ M. Kasten,²¹ Y. Kato,³⁷ Y. Kemp,²³ Cephart,¹³ D. Khazins,¹² V. Khotilovich,⁴⁸ B. Kilminster,⁴⁴ B. J. Kim,²⁵

Results: $M(D_s) - M(D^+)$

- $99.41 \pm 0.38 \pm 0.21 \text{ MeV}/c^2$
- PDG: $99.2 \pm 0.5 \text{ MeV}/c^2$

Level 1 drift chamber trigger (XFT)



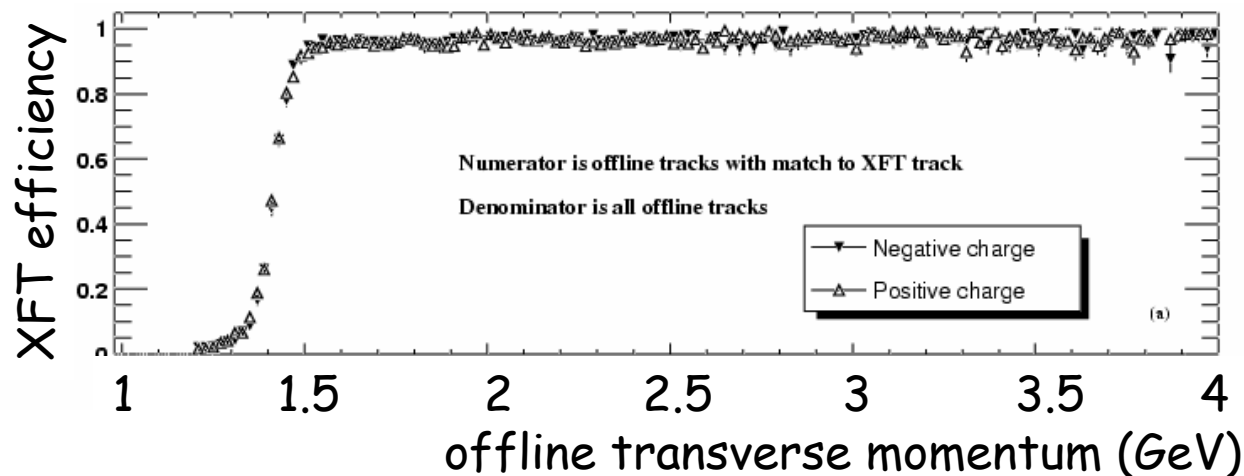
Finds $p_T > 1.5 \text{ GeV}$
tracks in $1.9 \mu\text{s}$

For every bunch
crossing (132 ns)!

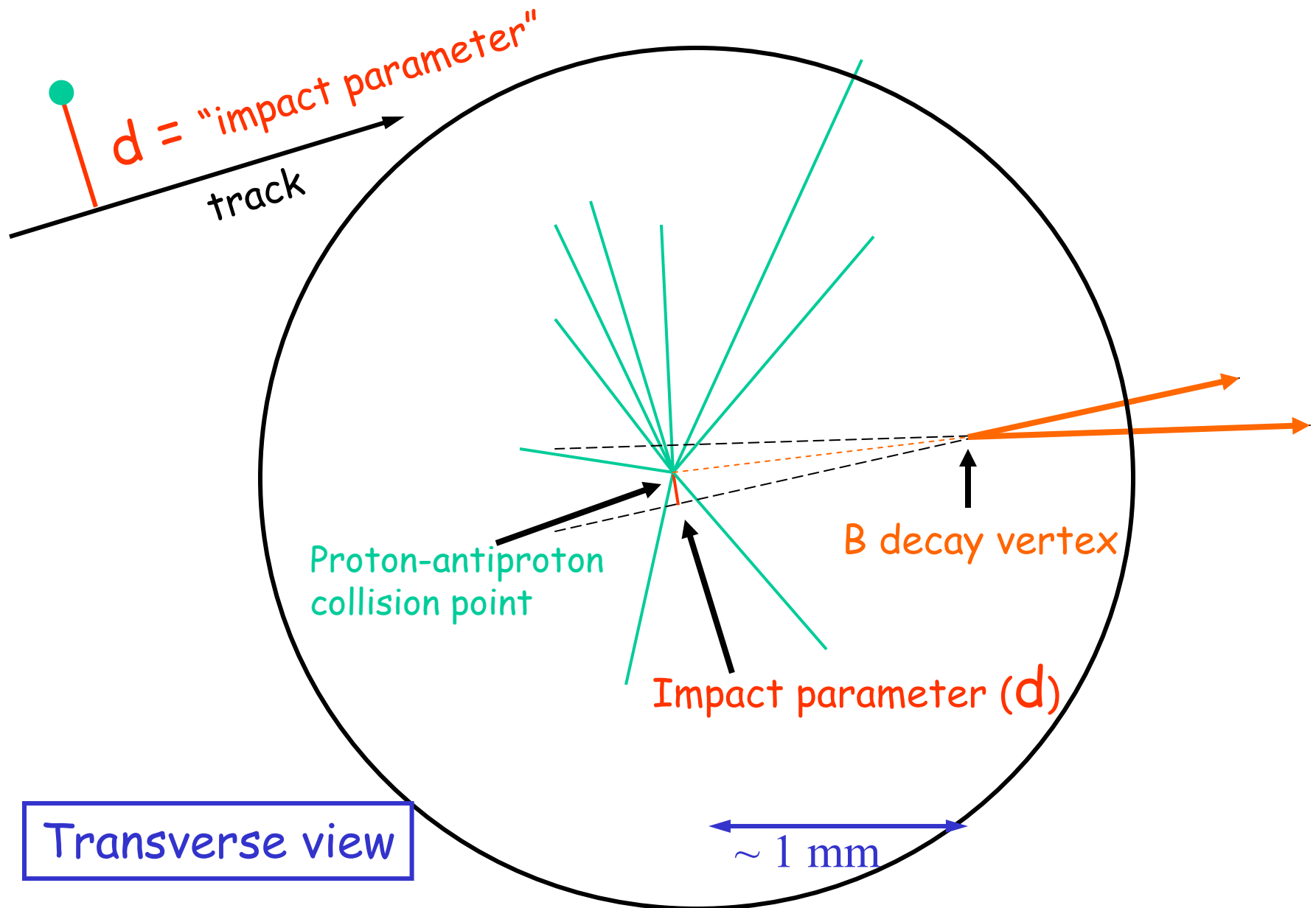
$$\sigma(1/p_T) = 1.7\%/\text{GeV}$$

$$\sigma(\phi_0) = 5 \text{ mrad}$$

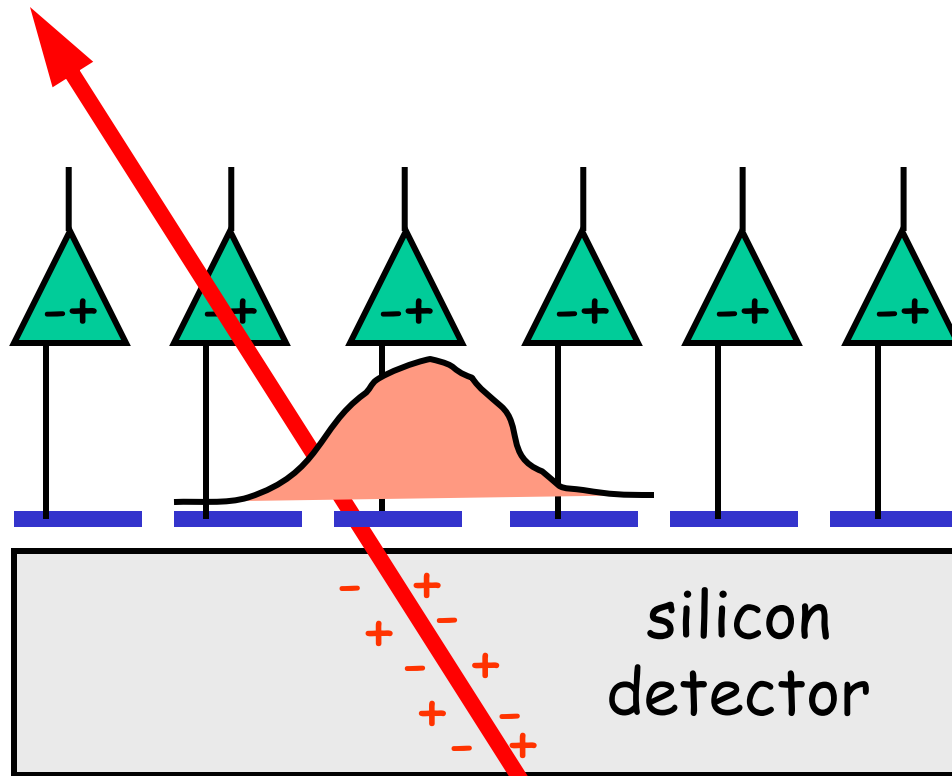
96% efficiency



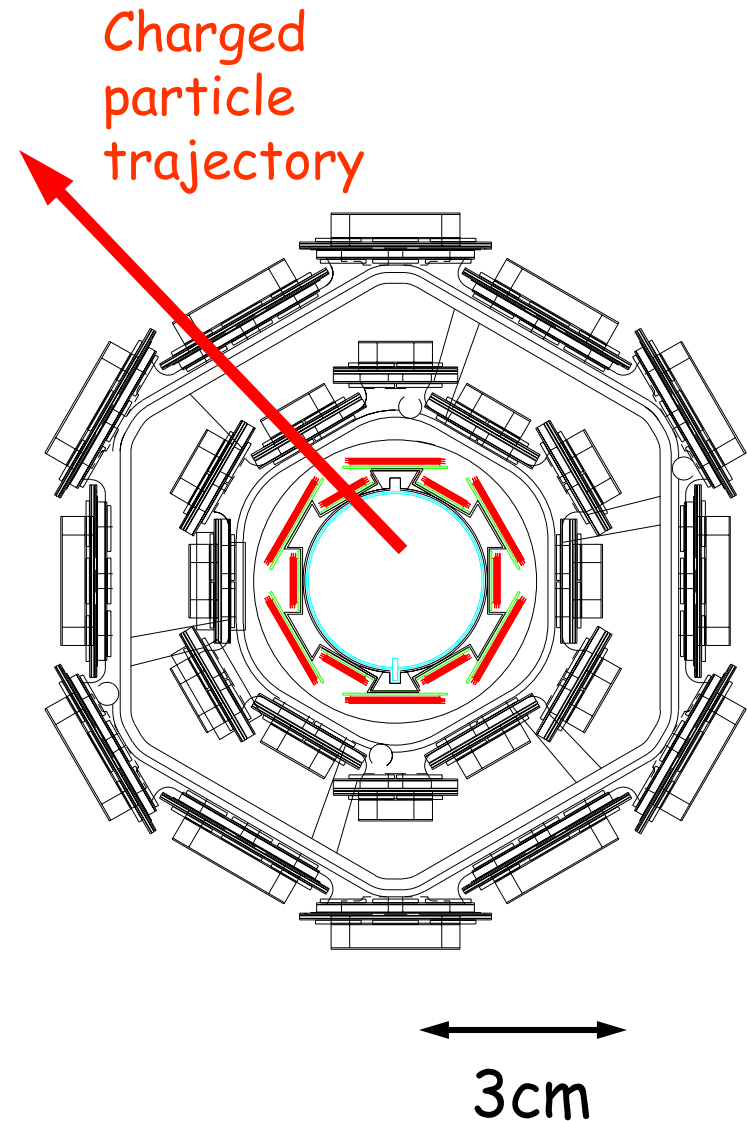
Exploit lifetime to select b,c decays



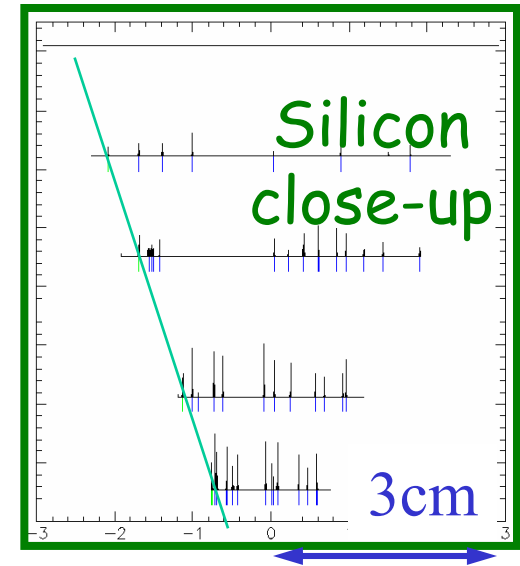
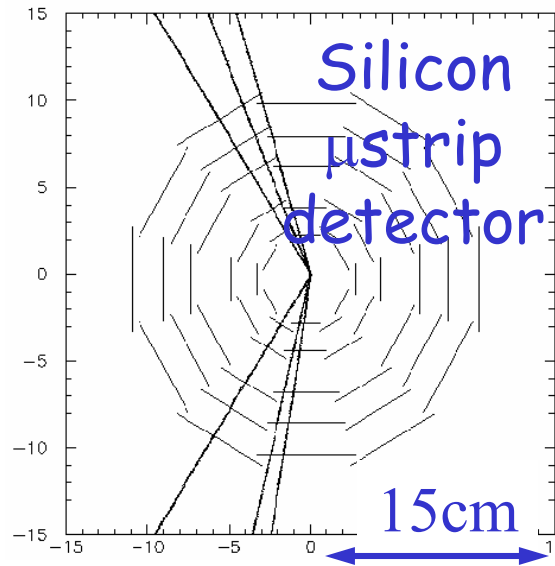
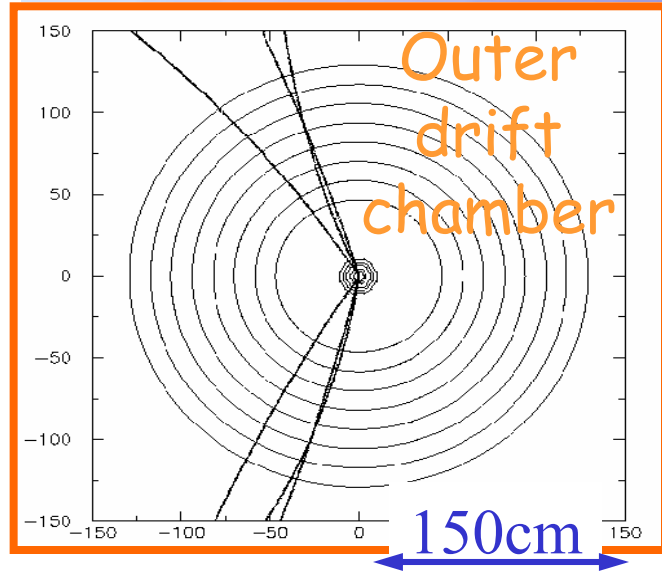
Position measurement ("hit") for charged particle



"hit" = charge centroid



Silicon trigger problem synopsis



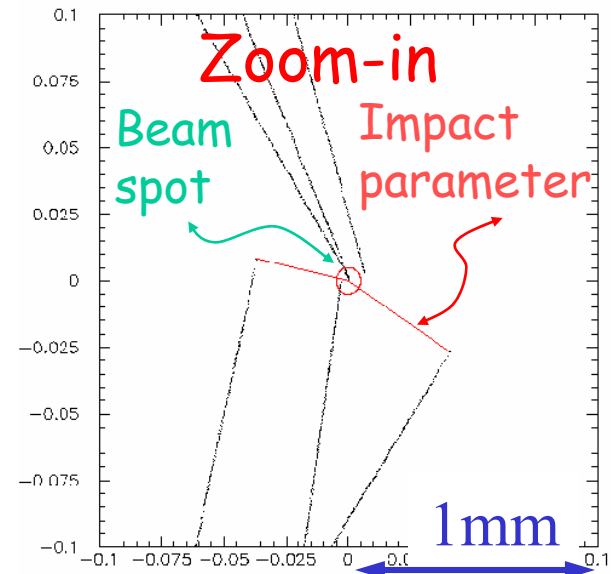
Input (every Level 1 accept):

outer drift chamber trajectories

silicon pulse height for each channel

Output (about 20 microseconds later):
trajectories that use silicon points

impact parameter: $\sigma(d)=35\mu\text{m}$

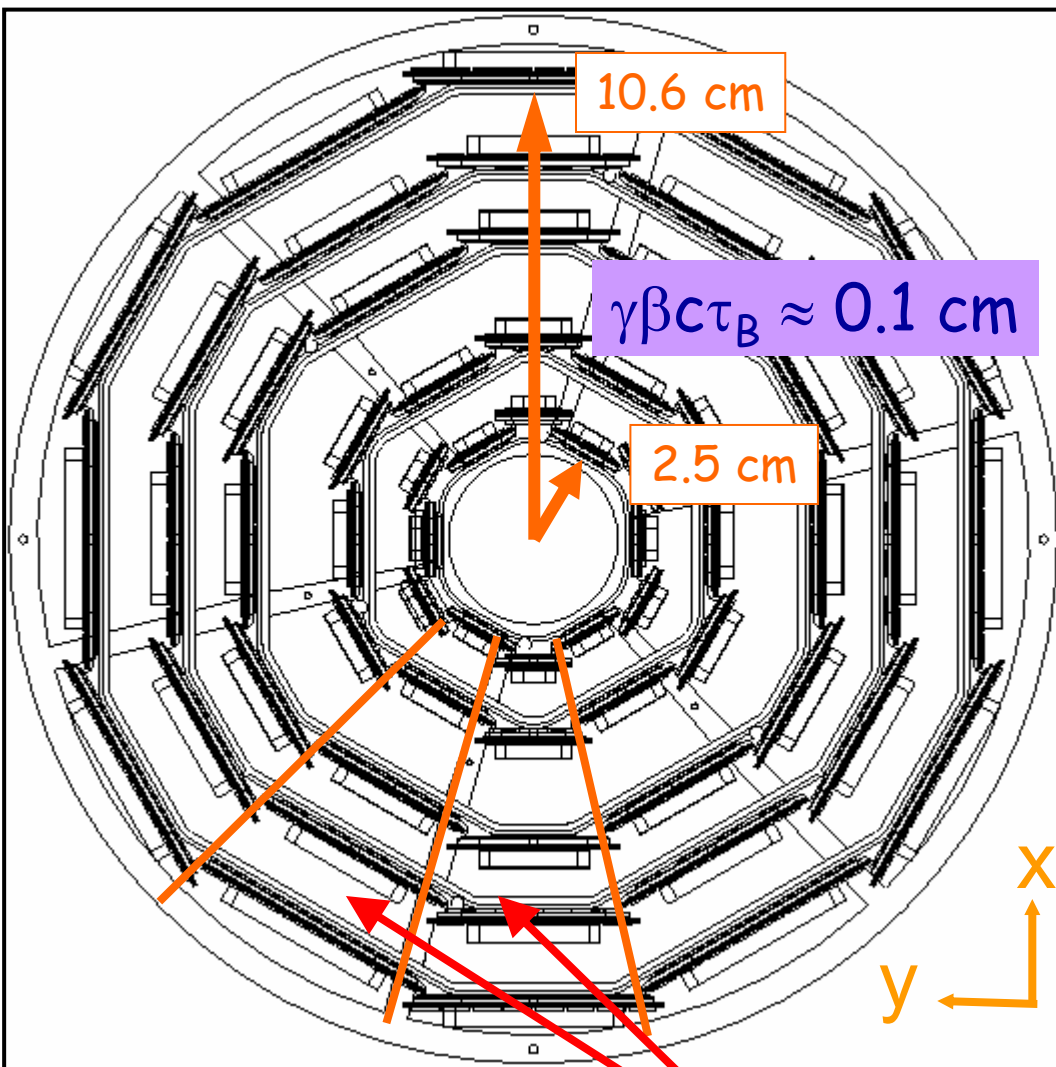


Doing silicon tracking quickly

Three key features of SVT allow us to do in tens of microseconds what typically takes software hundreds of milliseconds:

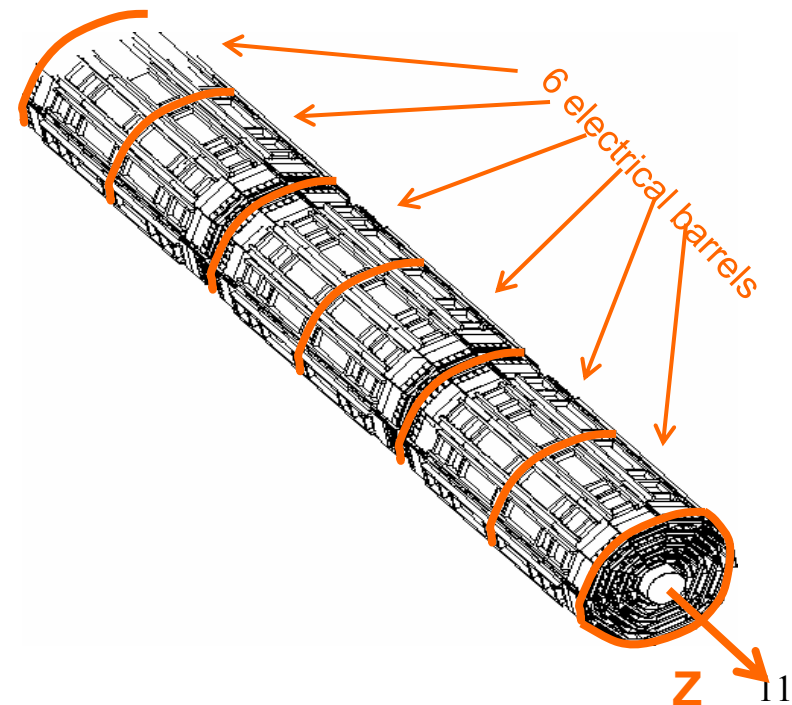
- Parallel/pipelined architecture
- Custom VLSI pattern recognition
- Linear track fit in fast FPGAs

Trick #1: symmetry allows parallelism



Note "wedge" symmetry

Symmetric, modular geometry of silicon vertex detector lends itself to parallel processing



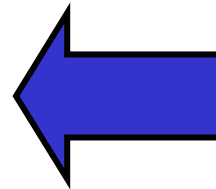
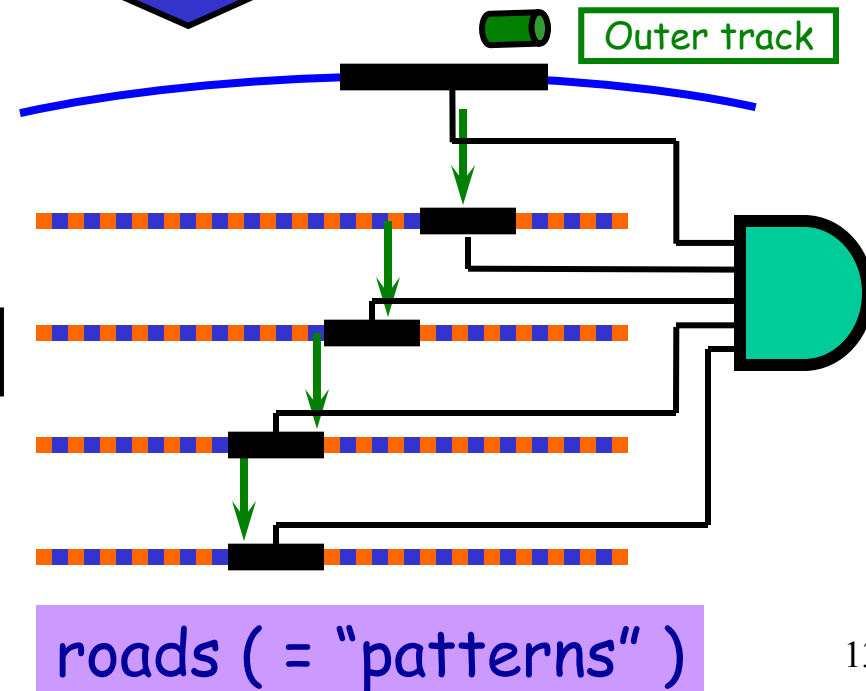
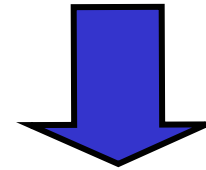
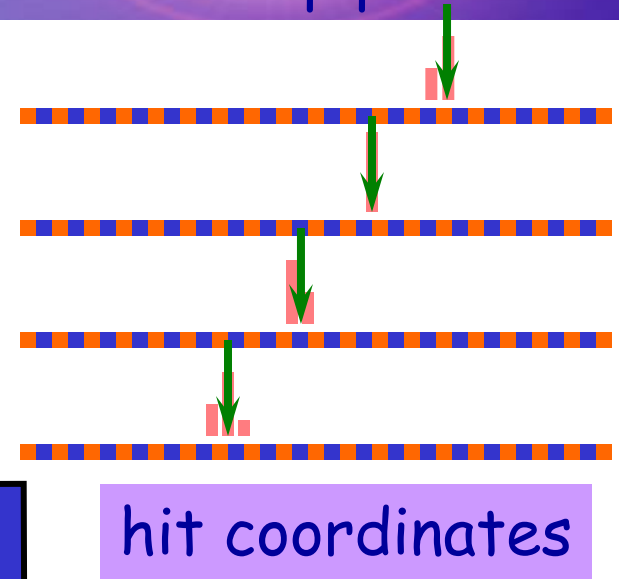
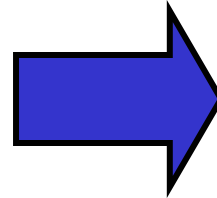
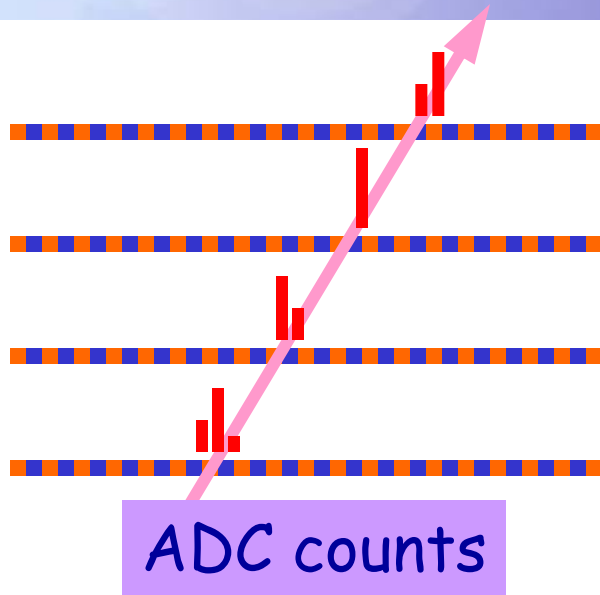
SVT data volume requires parallelism



Reduces gigabytes/second to megabytes/second

Peak (avg): 20 (0.5) GB/s $\longrightarrow$ 100 (1.5) MB/s

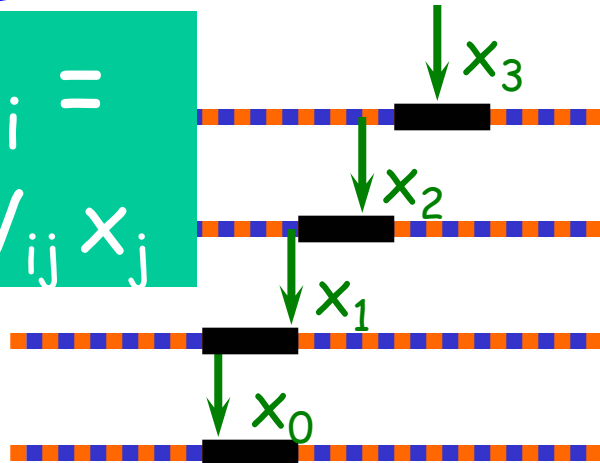
Each 1/12 of detector is processed in its own pipeline



C_{outer}, ϕ_{outer}

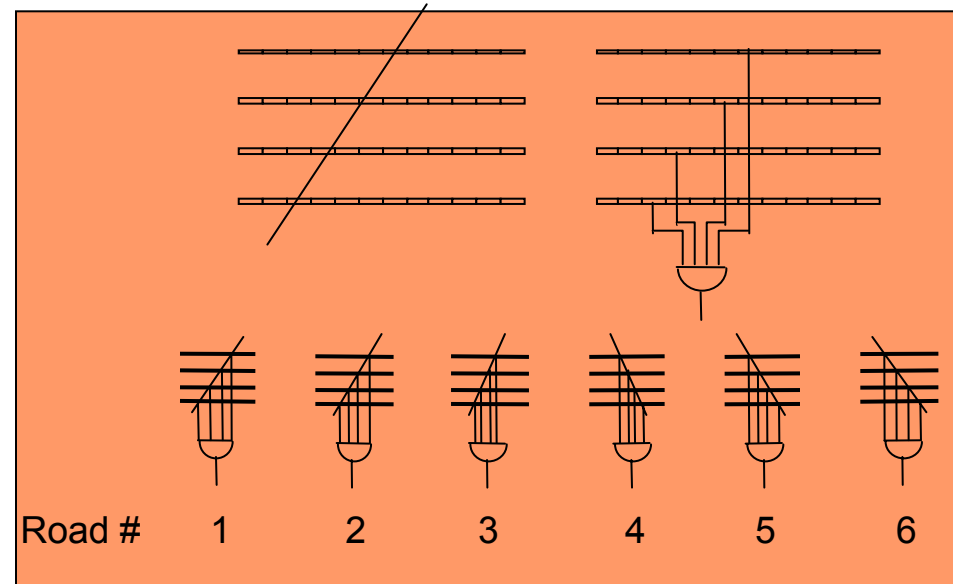
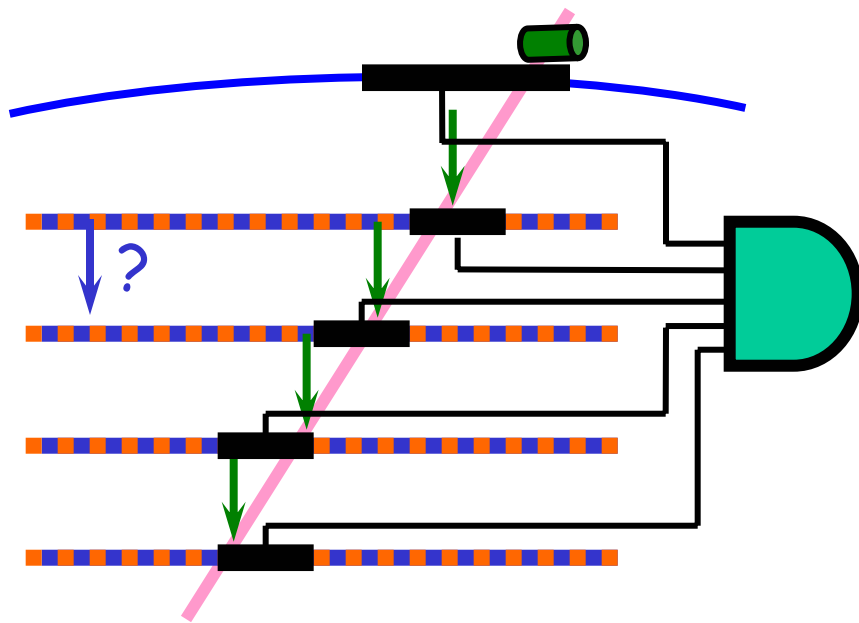


$$P_i = \sum V_{ij} x_j$$



Fitted tracks: $\vec{P} = (c, \phi, d, \chi^2)$

2nd trick: streamlined track finding



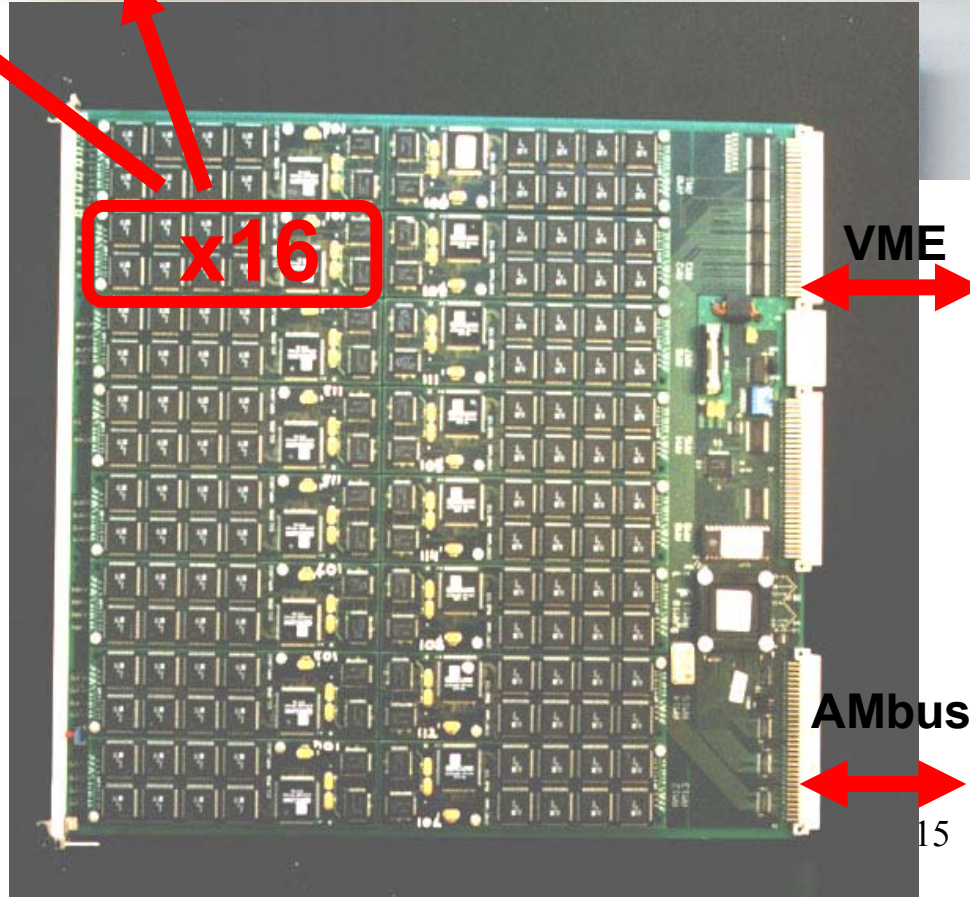
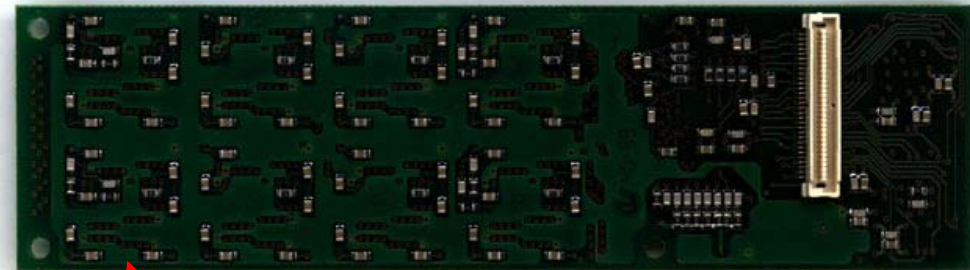
The way we find tracks is a cross between

- searching predefined roads
- playing BINGO

$$\text{Time} \sim A * N_{\text{hits}} + B * N_{\text{matchedroads}}$$

B	I	N	G	O
2	17	35	48	61
10	21	39	53	66
14	20	free	55	65
8	25	41	52	62
6	16	37	46	67

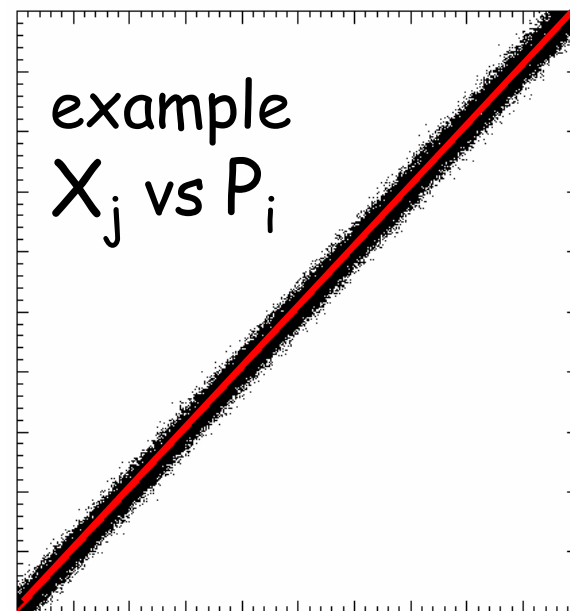
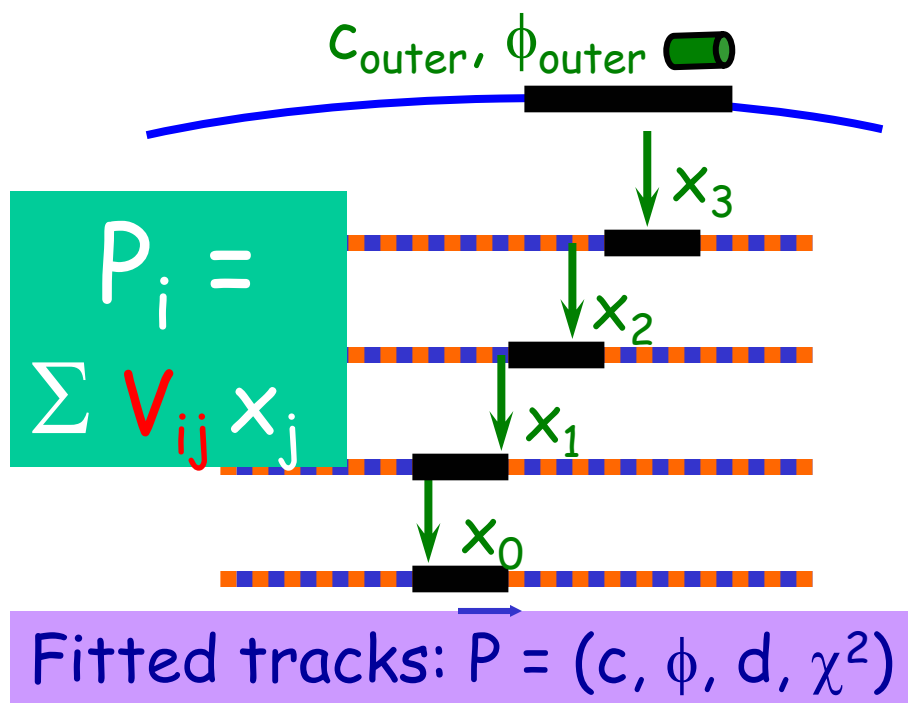
Custom VLSI AMchip (pattern recognition)



Trick #3: linear fit

Circle($\vec{P}$) $\cap$ Planes at points $\vec{x}$
 $\vec{x}$ not in general linear in $\vec{P}$

But for $P > 2 \text{ GeV}$, $d < 1 \text{ mm}$,
 linear fit biases $d \sim \text{few } \%$
 $\Rightarrow$ no problem for trigger



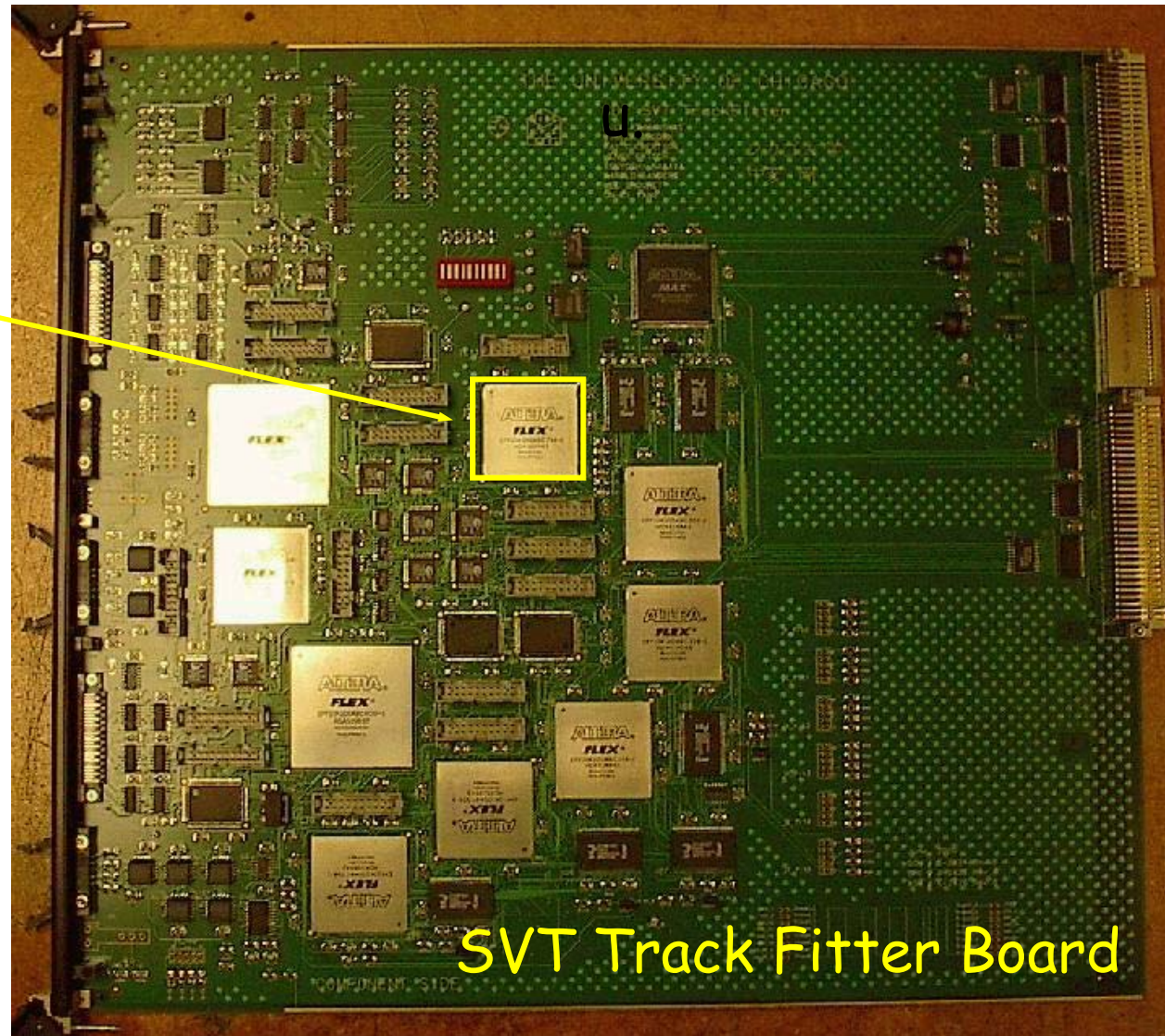
We derive V_{ij} by linear regression to Monte Carlo data

Trick #3a: use road as a hint
 precompute $V_{ij} X_j^{\text{road}}$
 $\Rightarrow 250 \text{ nsec per fit !}$

Least squares fit is performed in FPGA

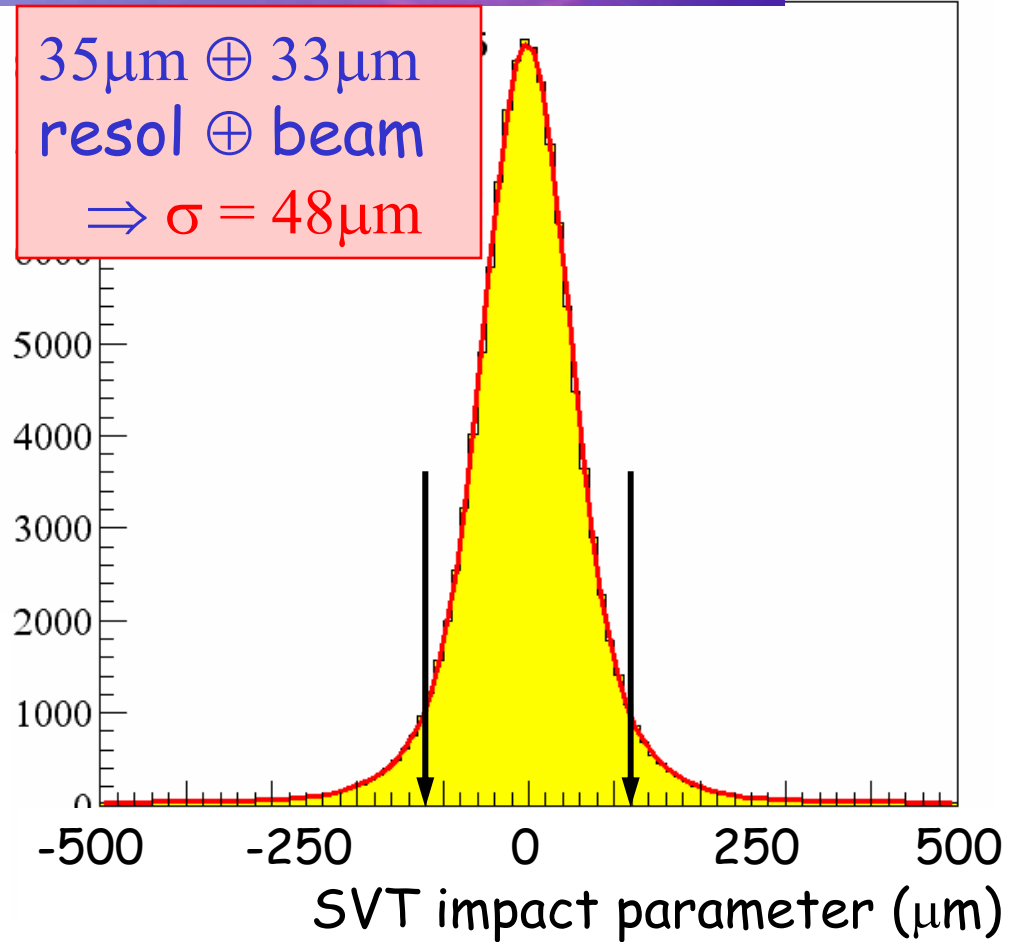
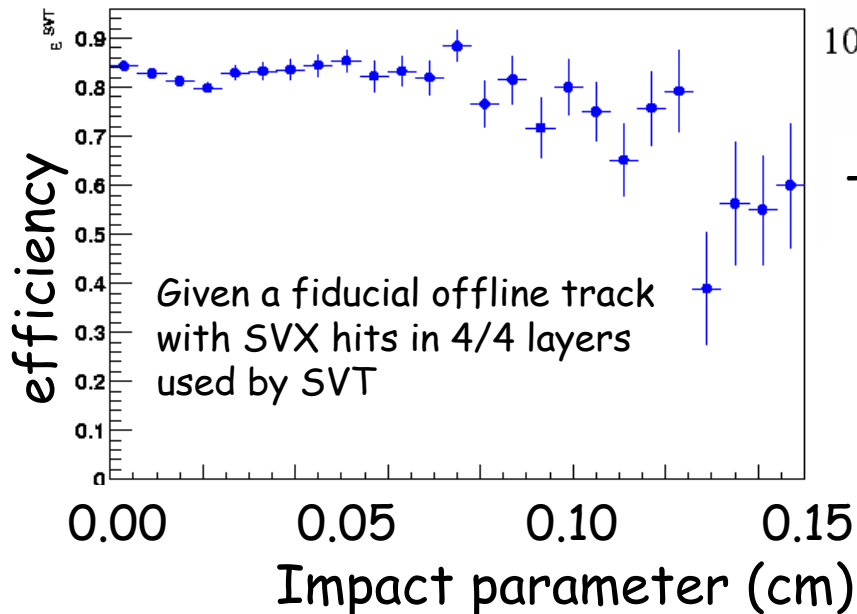
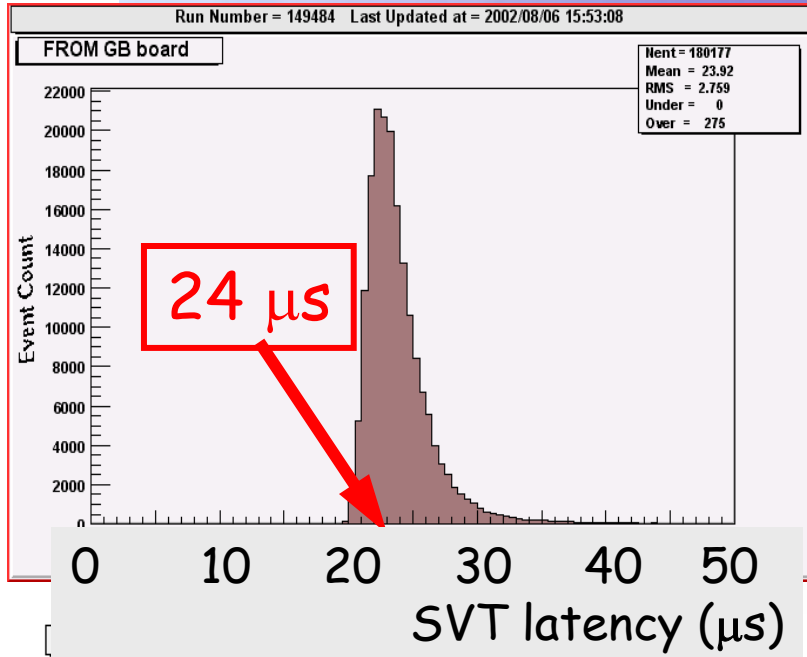
The 6 scalar products are
computed in parallel

Each fit done in 250nsec



SVT Track Fitter Board

Performance

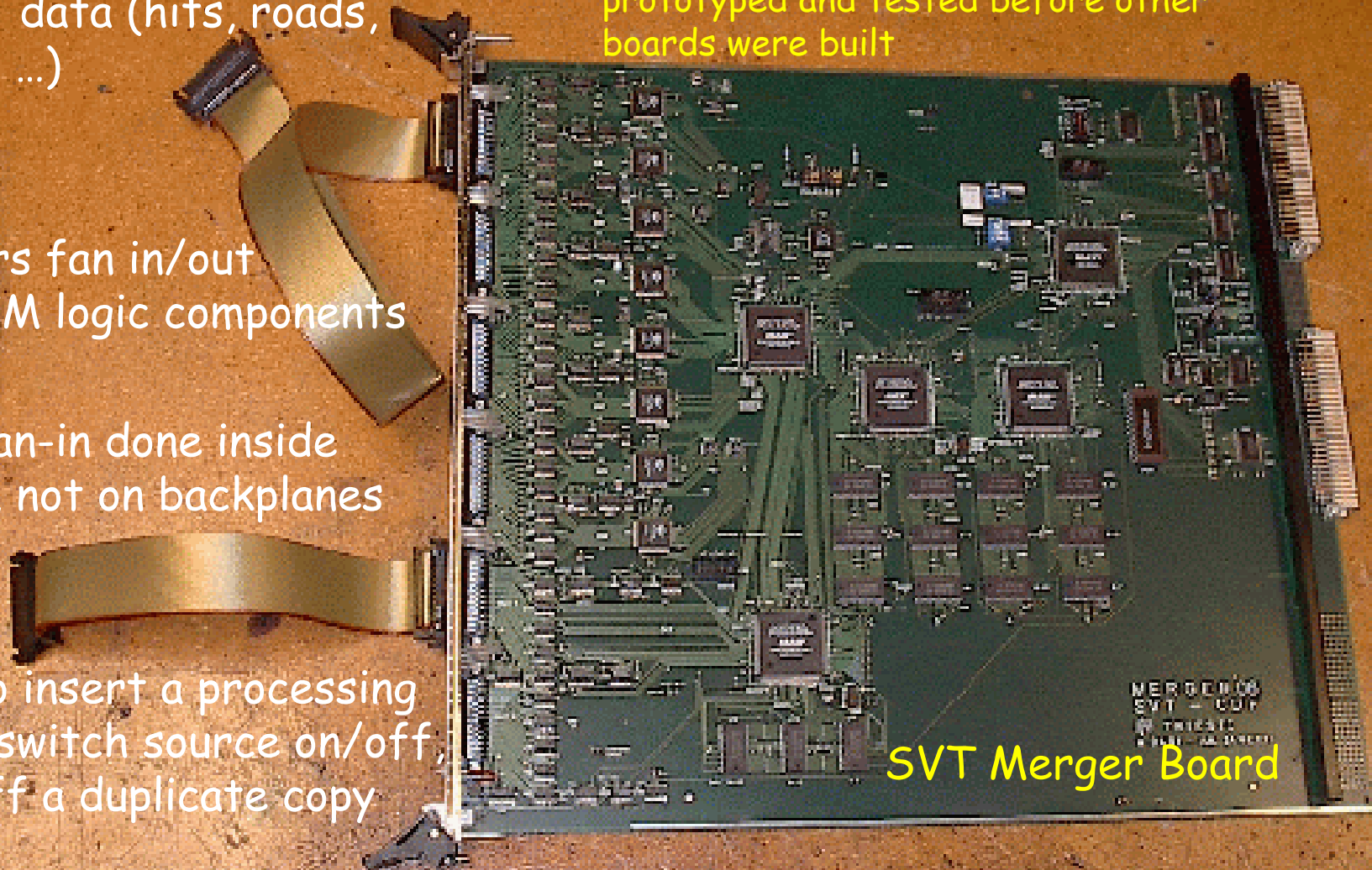


N.B.: lots of trigger & detector work to keep efficiency high
 $\rightarrow$ Lester Miller's talk on CDF silicon

Merger & cable capture essence of SVT architecture

- ❖ Universal cable/format for all SVT data (hits, roads, tracks, ...)
- ❖ Mergers fan in/out like NIM logic components
- ❖ Data fan-in done inside FPGAs, not on backplanes
- ❖ Easy to insert a processing stage, switch source on/off, split off a duplicate copy

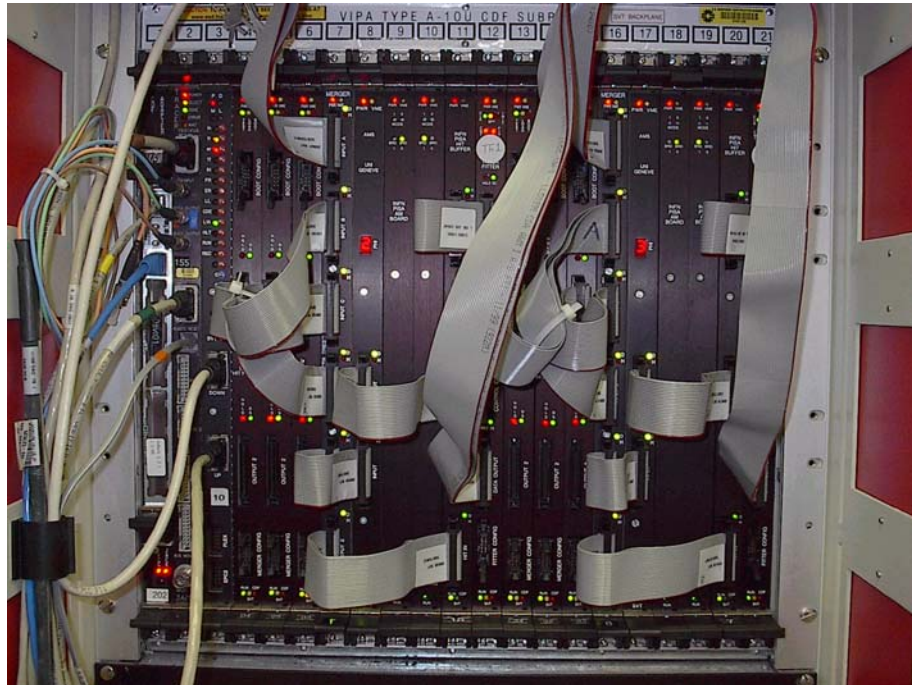
The board to move the data around was prototyped and tested before other boards were built



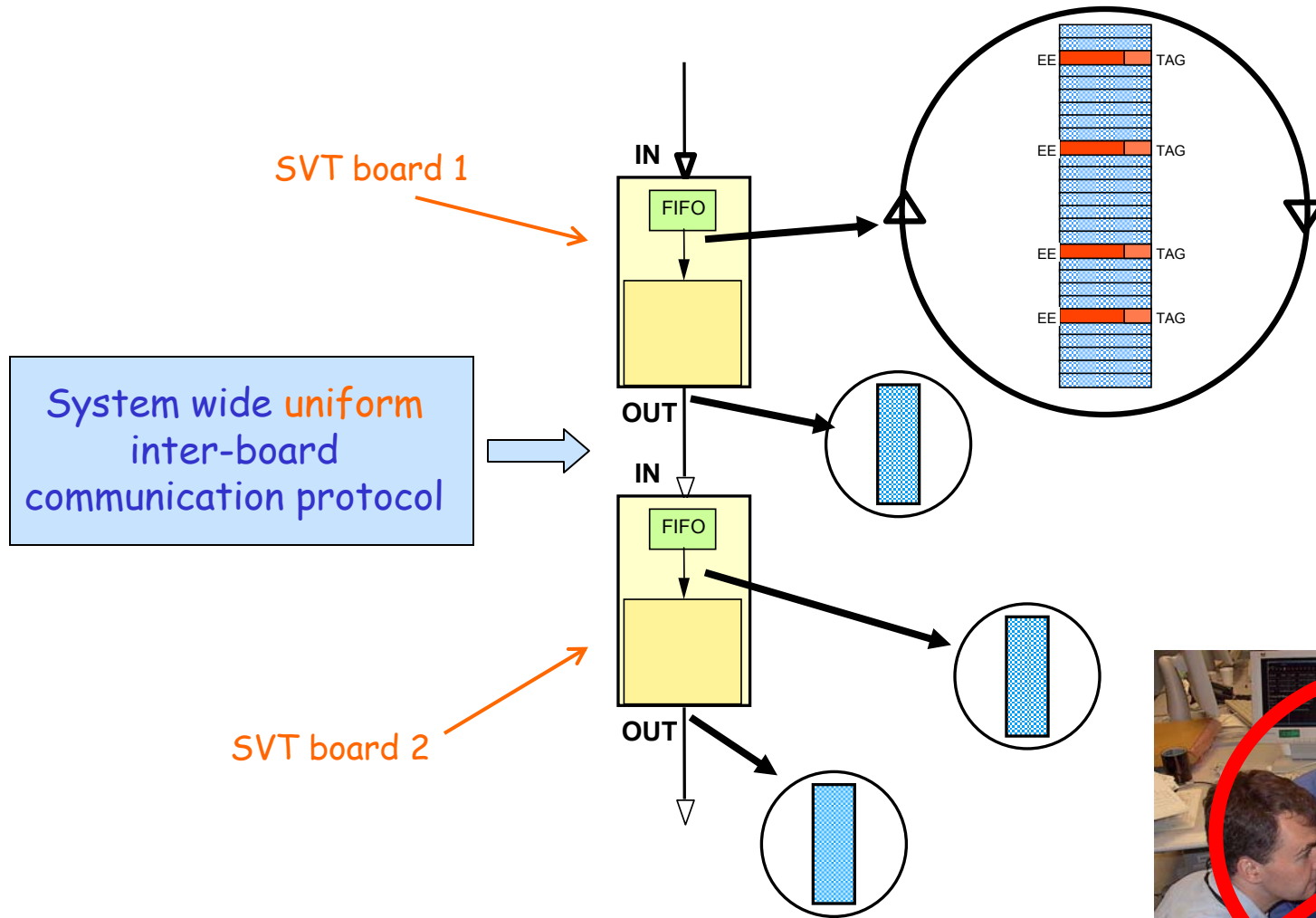
Universal cable -> can adapt quickly, as with NIM logic

Most of SVT's cabling was carefully planned a priori

But the flexibility to adapt to the unforeseen was a big plus during commissioning

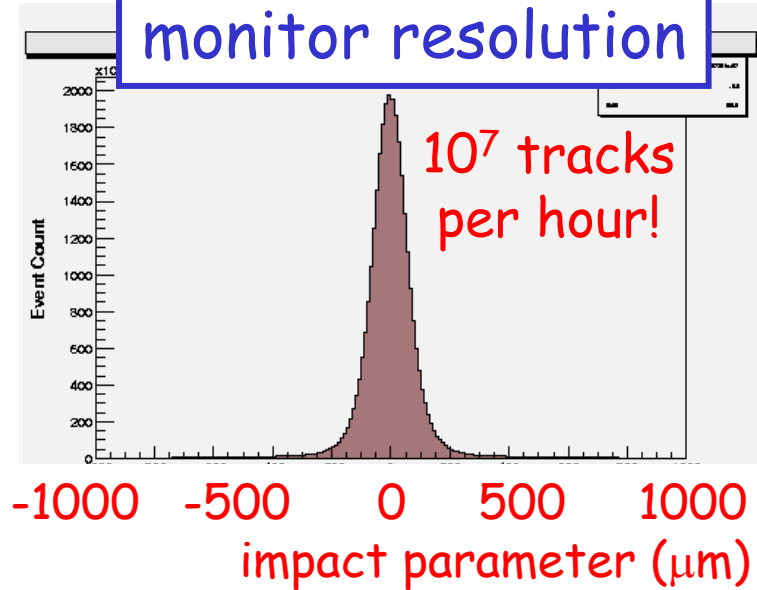


Circular buffers monitor every data link: like a built-in logic analyzer

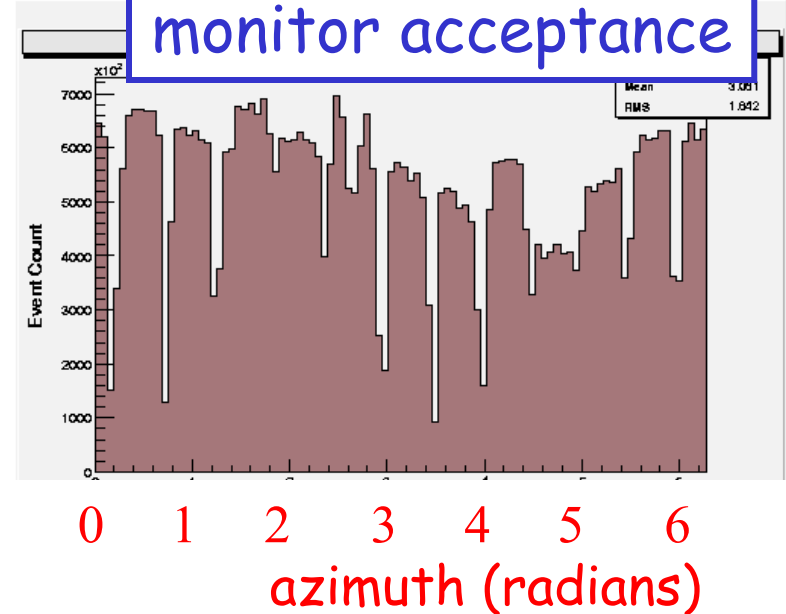


On-crate monitoring of circular buffers

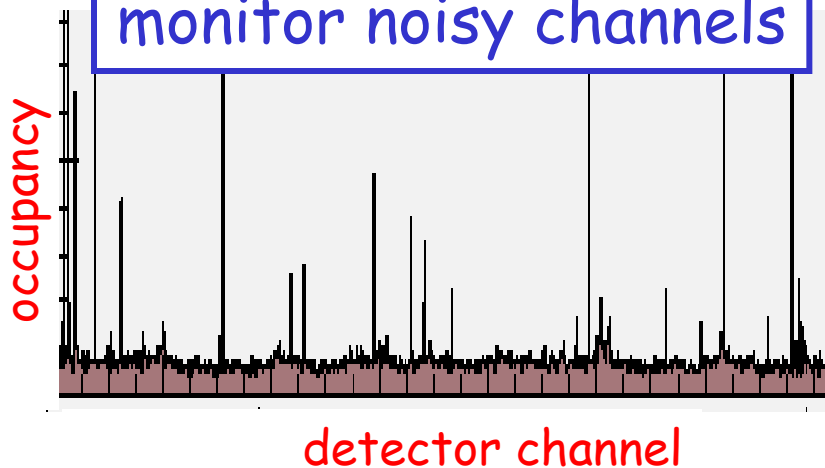
monitor resolution



monitor acceptance



monitor noisy channels

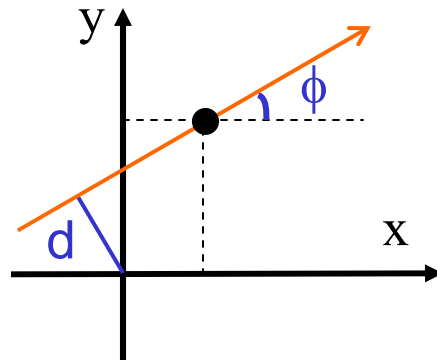


Sample hits, roads,
tracks at high rate

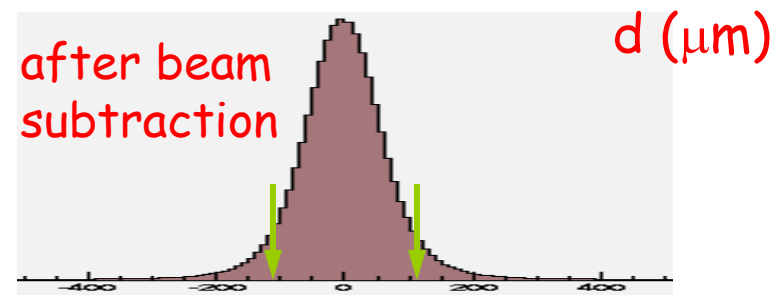
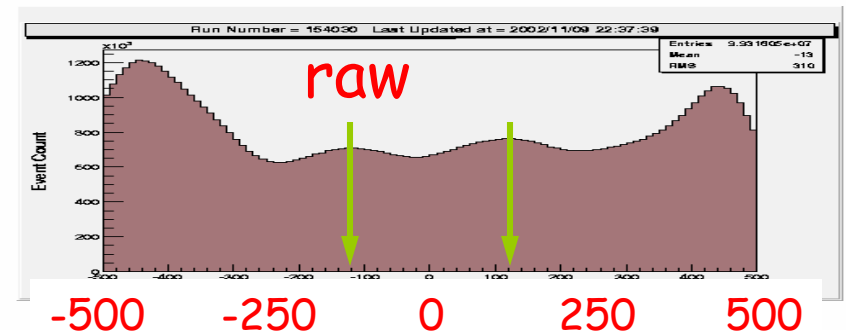
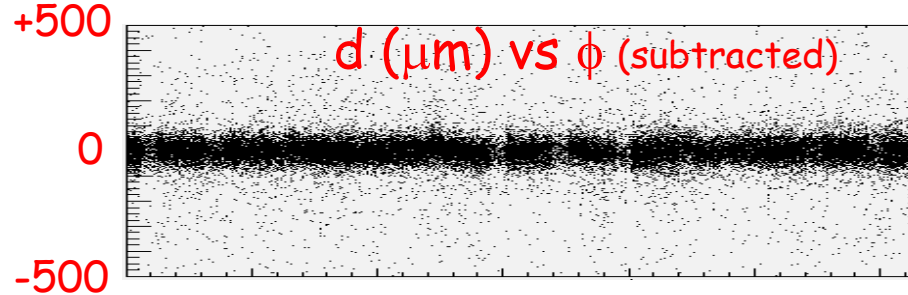
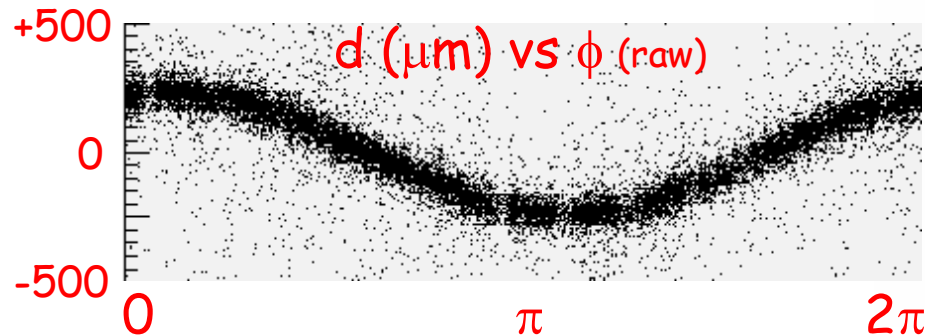
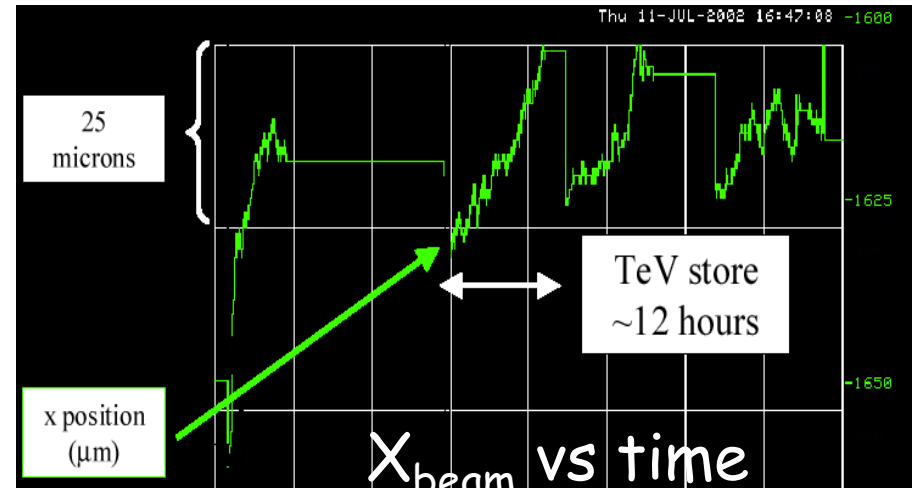
Check boards against
emulation software

Fit for beam position ...

Online beamline fit / correction



$$\langle d \rangle = Y_{\text{beam}} \cos \phi - X_{\text{beam}} \sin \phi$$



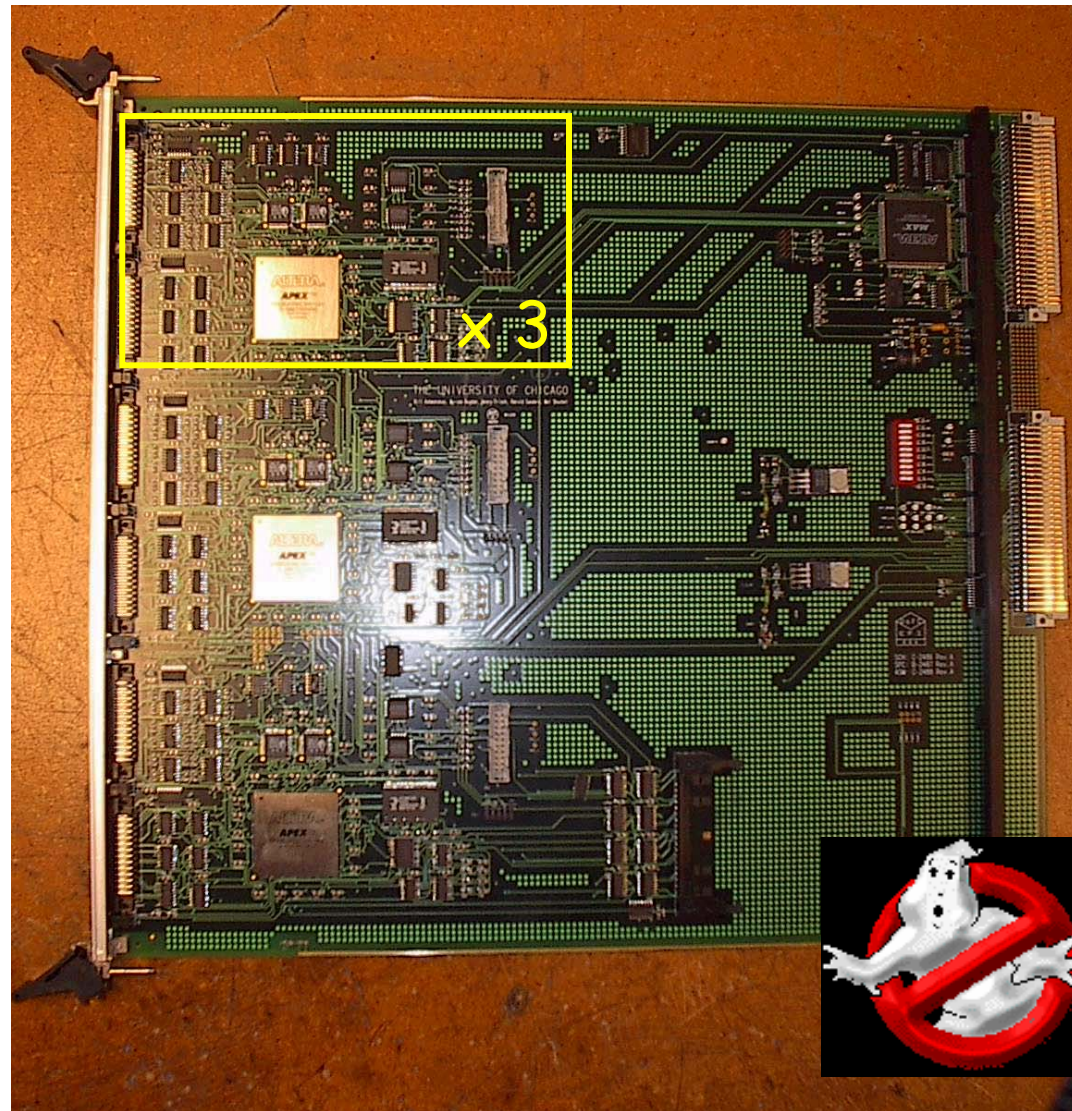
SVT board-on-a-chip

Input + output + one
Altera APEX FPGA

- Modern FPGAs have impressive capabilities

Swiss army knife:

- Subtract beam offset
- Filter duplicate ("ghost") tracks
- Read diagnostic data into DAQ
- Measure timing



Why SVT succeeded

- Performance:
 - Parallel/pipelined architecture
 - Custom VLSI pattern recognition
 - Linear track fit in fast FPGAs
- Reliability:
 - Easy to sink/source test data (many boards can self-test)
 - Modular design; universal, well-tested data link & fan-in/out
 - Extensive on-crate monitoring during beam running
 - Detailed CAD simulation before prototyping
 - ◆ See poster by Mircea Bogdan
- Flexibility:
 - System can operate with some (or all) inputs disabled
 - Building-block design: can add/replace processing steps
 - Modern FPGAs permit unforeseen algorithm changes
- Key: design system for easy testing/commissioning